8-bit static shift register Rev. 11 — 1 December 2021

### 1. General description

The HEF4021B is an 8-bit static shift register (parallel-to-serial converter) with a synchronous serial data input (DS), a clock input (CP), an asynchronous active HIGH parallel load input (PL), eight asynchronous parallel data inputs (D0 to D7) and buffered parallel outputs from the last three stages (Q5 to Q7). Each register stage is a D-type master-slave flip-flop with a set direct (SD) and clear direct (CD) input. Information on D0 to D7 is asynchronously loaded into the register while PL is HIGH, independent of CP and DS. When PL is LOW, data on DS is shifted into the first register position and all the data in the register is shifted one position to the right on the LOW-to-HIGH transition of CP. Schmitt trigger action makes the clock input highly tolerant of slower rise and fall times.

The device operates over a recommended V<sub>DD</sub> power supply range of 3 V to 15 V referenced to V<sub>SS</sub> (usually ground). Unused inputs must be connected to V<sub>DD</sub>, V<sub>SS</sub>, or another input.

### 2. Features and benefits

- Wide supply voltage range from 3.0 V to 15.0 V
- CMOS low power dissipation
- High noise immunity
- Tolerant of slower rise and fall times
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Complies with JEDEC standard JESD 13-B
- ESD protection:
  - HBM JESD22-A114F exceeds 2000 V
  - MM JESD22-A115-B exceeds 200 V
- Specified from -40 °C to +85 °C and from -40 °C to +125 °C

### 3. Ordering information

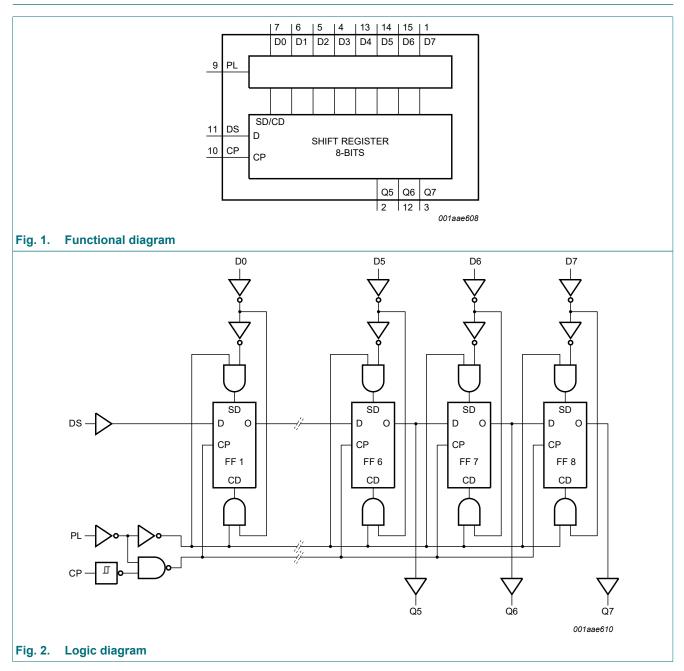
#### Table 1. Ordering information

Type number	Package								
	Temperature range	Name	Description	Version					
HEF4021BT	-40 °C to +125 °C	SO16	plastic small outline package; 16 leads; body width 3.9 mm	SOT109-1					
HEF4021BTT	-40 °C to +125 °C	TSSOP16	plastic thin shrink small outline package; 16 leads; body width 4.4 mm	SOT403-1					

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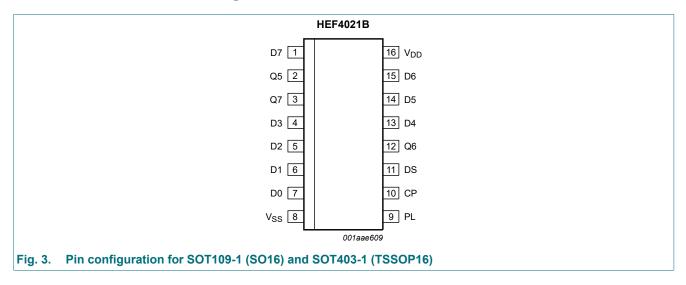
#### 8-bit static shift register

# 4. Functional diagram



# 5. Pinning information

### 5.1. Pinning



### 5.2. Pin description

#### Table 2. Pin description

Symbol	Pin	Description
Q5, Q6, Q7	2, 12, 3	buffered parallel output from the last three stages
D0, D1, D2, D3, D4, D5, D6, D7	7, 6, 5, 4, 13, 14,15, 1	parallel data input
V <sub>SS</sub>	8	ground supply voltage
PL	9	parallel load input
СР	10	clock input (LOW-to-HIGH edge-triggered)
DS	11	serial data input
V <sub>DD</sub>	16	supply voltage

### 6. Functional description

#### Table 3. Function table

H = HIGH voltage level; L = LOW voltage level; X = don't care;

 $\uparrow$  = LOW to HIGH clock transition;  $\downarrow$  = HIGH to LOW clock transition;

data n = data (HIGH or LOW) on the DS input at the  $n^{th} \uparrow CP$  transition.

Number of clock	Inputs			Outputs		
transitions	СР	DS	PL	Q5	Q6	Q7
Serial operation	1		I.	1	1	I.
1	1	data 1	L	X	X	Х
2	↑	data 2	L	Х	Х	Х
3	1	data 3	L	Х	Х	Х
6	1	Х	L	data 1	Х	Х
7	1	Х	L	data 2	data 1	Х
8	↑	Х	L	data 3	data 2	data 1
	Ļ	Х	L	no change	no change	no change
Parallel operation	I		1			1
	X	X	Н	D5	D6	D7

### 7. Limiting values

#### Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>DD</sub>	supply voltage		-0.5	+18	V
I <sub>IK</sub>	input clamping current	$V_{\rm I}$ < -0.5 V or $V_{\rm I}$ > $V_{\rm DD}$ + 0.5 V	-	±10	mA
VI	input voltage		-0.5	V <sub>DD</sub> + 0.5	V
I <sub>OK</sub>	output clamping current	$V_{O}$ < -0.5 V or $V_{O}$ > $V_{DD}$ + 0.5 V	-	±10	mA
I <sub>I/O</sub>	input/output current		-	±10	mA
I <sub>DD</sub>	supply current		-	50	mA
T <sub>stg</sub>	storage temperature		-65	+150	°C
T <sub>amb</sub>	ambient temperature		-40	+125	°C
P <sub>tot</sub>	total power dissipation	T <sub>amb</sub> -40 °C to +125 °C [1]	-	500	mW
Р	power dissipation	per output	-	100	mW

For SOT109-1 (SO16) package: P<sub>tot</sub> derates linearly with 12.4 mW/K above 110 °C.
 For SOT403-1 (TSSOP16) package: P<sub>tot</sub> derates linearly with 8.5 mW/K above 91 °C.

# 8. Recommended operating conditions

Tabl	e 5	. Rec	omm	ended	operating	conditions		
-	-		_				-	

Symbol	Parameter	Conditions	Min	Тур	Мах	Unit
V <sub>DD</sub>	supply voltage		3	-	15	V
VI	input voltage		0	-	V <sub>DD</sub>	V
T <sub>amb</sub>	ambient temperature	in free air	-40	-	+125	°C
Δt/ΔV	input transition rise and fall rate	V <sub>DD</sub> = 5 V	-	-	3.75	µs/V
		V <sub>DD</sub> = 10 V	-	-	0.5	µs/V
		V <sub>DD</sub> = 15 V	-	-	0.08	μs/V

### 9. Static characteristics

#### Table 6. Static characteristics

 $V_{SS}$  = 0 V;  $V_{I}$  =  $V_{SS}$  or  $V_{DD}$  unless otherwise specified.

Symbol	Parameter	Conditions	V <sub>DD</sub>	T <sub>amb</sub> =	-40 °C	T <sub>amb</sub> =	+25 °C	T <sub>amb</sub> =	+85 °C	T <sub>amb</sub> = ·	+125 °C	Unit
				Min	Max	Min	Мах	Min	Max	Min	Max	
V <sub>IH</sub>	HIGH-level	I <sub>O</sub>   < 1 μΑ	5 V	3.5	-	3.5	-	3.5	-	3.5	-	V
	input voltage		10 V	7.0	-	7.0	-	7.0	-	7.0	-	V
			15 V	11.0	-	11.0	-	11.0	-	11.0	-	V
V <sub>IL</sub>	LOW-level	I <sub>0</sub>   < 1 μΑ	5 V	-	1.5	-	1.5	-	1.5	-	1.5	V
	input voltage		10 V	-	3.0	-	3.0	-	3.0	-	3.0	V
			15 V	-	4.0	-	4.0	-	4.0	-	4.0	V
V <sub>OH</sub>	HIGH-level	I <sub>O</sub>   < 1 μΑ	5 V	4.95	-	4.95	-	4.95	-	4.95	-	V
	output voltage		10 V	9.95	-	9.95	-	9.95	-	9.95	-	V
	voltage		15 V	14.95	-	14.95	-	14.95	-	14.95	-	V
V <sub>OL</sub>	LOW-level  I <sub>O</sub>   output voltage	I <sub>O</sub>   < 1 μΑ	5 V	-	0.05	-	0.05	-	0.05	-	0.05	V
			10 V	-	0.05	-	0.05	-	0.05	-	0.05	V
			15 V	-	0.05	-	0.05	-	0.05	-	0.05	V
I <sub>OH</sub>	HIGH-level	V <sub>O</sub> = 2.5 V	5 V	-	-1.7	-	-1.4	-	-1.1	-	-1.1	mA
	output current	V <sub>O</sub> = 4.6 V	5 V	-	-0.64	-	-0.5	-	-0.36	-	-0.36	mA
		V <sub>O</sub> = 9.5 V	10 V	-	-1.6	-	-1.3	-	-0.9	-	-0.9	mA
		V <sub>O</sub> = 13.5 V	15 V	-	-4.2	-	-3.4	-	-2.4	-	-2.4	mA
I <sub>OL</sub>	LOW-level	V <sub>O</sub> = 0.4 V	5 V	0.64	-	0.5	-	0.36	-	0.36	-	mA
	output current	V <sub>O</sub> = 0.5 V	10 V	1.6	-	1.3	-	0.9	-	0.9	-	mA
		V <sub>O</sub> = 1.5 V	15 V	4.2	-	3.4	-	2.4	-	2.4	-	mA
l <sub>l</sub>	input leakage current	V <sub>DD</sub> = 15 V	15 V	-	±0.1	-	±0.1	-	±1.0	-	±1.0	μA
I <sub>DD</sub>	supply	I <sub>O</sub> = 0 A	5 V	-	5	-	5	-	150	-	150	μA
	current		10 V	-	10	-	10	-	300	-	300	μA
			15 V	-	20	-	20	-	600	-	600	μA
CI	input capacitance		-	-	-	-	7.5	-	-	-	-	pF

# **10. Dynamic characteristics**

#### Table 7. Dynamic characteristics

 $V_{SS} = 0 V$ ;  $T_{amb} = 25 \degree C$  unless otherwise specified; for test circuit see Fig. 7.

Symbol	Parameter	Conditions	V <sub>DD</sub>	Extrapolation formula[1]	Min	Тур	Max	Unit
<sup>t</sup> PHL	HIGH to LOW	CP to Qn; see Fig. 4	5 V	98 ns + (0.55 ns/pF)C <sub>L</sub>	-	125	250	ns
	propagation delay		10 V	44 ns + (0.23 ns/pF)C <sub>L</sub>	-	55	110	ns
			15 V	32 ns + (0.16 ns/pF)C <sub>L</sub>	-	40	80	ns
		PL to Qn; see Fig. 4	5 V	93 ns + (0.55 ns/pF)C <sub>L</sub>	-	120	240	ns
			10 V	44 ns + (0.23 ns/pF)C <sub>L</sub>	-	55	110	ns
			15 V	32 ns + (0.16 ns/pF)C <sub>L</sub>	-	40	80	ns
PLH	LOW to HIGH	CP to Qn; see Fig. 4	5 V	88 ns + (0.55 ns/pF)C <sub>L</sub>	-	115	230	ns
	propagation delay		10 V	39 ns + (0.23 ns/pF)C <sub>L</sub>	-	50	100	ns
			15 V	32 ns + (0.16 ns/pF)C <sub>L</sub>	-	40	80	ns
		PL to Qnl; see Fig. 4	5 V	78 ns + (0.55 ns/pF)C <sub>L</sub>	-	105	210	ns
			10 V	39 ns + (0.23 ns/pF)C <sub>L</sub>	-	50	100	ns
			15 V	32 ns + (0.16 ns/pF)C <sub>L</sub>	-	40	80	ns
t	transition time	Qn; see <u>Fig. 4</u>	5 V	10 ns + (1.00 ns/pF)C <sub>L</sub>	-	60	120	ns
			10 V	9 ns + (0.42 ns/pF)C <sub>L</sub>	-	30	60	ns
			15 V	6 ns + (0.28 ns/pF)C <sub>L</sub>	-	20	40	ns
su	set-up time	DS to CP; see Fig. 5	5 V		+25	-15	-	ns
			10 V		+25	-10	-	ns
			15 V		+15	-5	-	ns
		Dn to PL; see Fig. 6	5 V		50	25	-	ns
			10 V		30	10	-	ns
			15 V		20	5	-	ns
ĥ	hold time	DS to CP; see Fig. 5	5 V		40	20	-	ns
			10 V		20	10	-	ns
			15 V		15	8	-	ns
		Dn to PL; see Fig. 6	5 V		+15	-10	-	ns
			10 V		15	0	-	ns
			15 V		15	0	-	ns
w	pulse width	CP = LOW;	5 V		70	35	-	ns
		minimum width; see <u>Fig. 5</u>	10 V		30	15	-	ns
			15 V		24	12	-	ns
		PL = HIGH;	5 V		70	35	-	ns
		minimum width; see <u>Fig. 6</u>	10 V		30	15	-	ns
			15 V		24	12	-	ns
rec	recovery time	PL input; see Fig. 6	5 V		50	10	-	ns
			10 V		40	5	-	ns
			15 V		35	5	-	ns

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Symbol	Parameter	Conditions	V <sub>DD</sub>	Extrapolation formula[1]	Min	Тур	Мах	Unit
f <sub>clk(max)</sub>	maximum clock	CP input; see <u>Fig. 5</u>	5 V		6	13	-	MHz
	frequency		10 V		15	30	-	MHz
			15 V		20	40	-	MHz

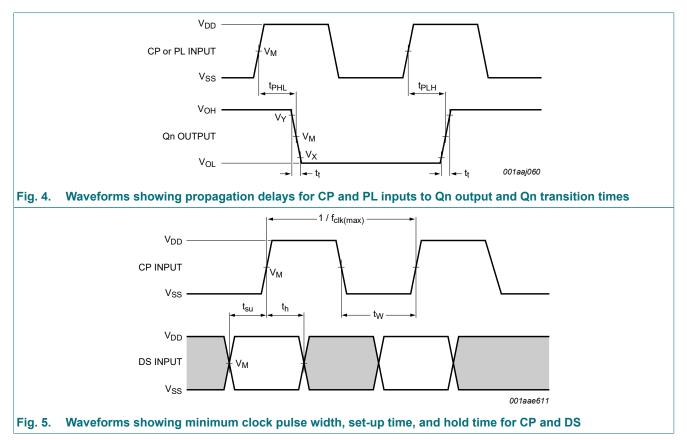
[1] The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown (C<sub>L</sub> in pF).

#### Table 8. Dynamic power dissipation P<sub>D</sub>

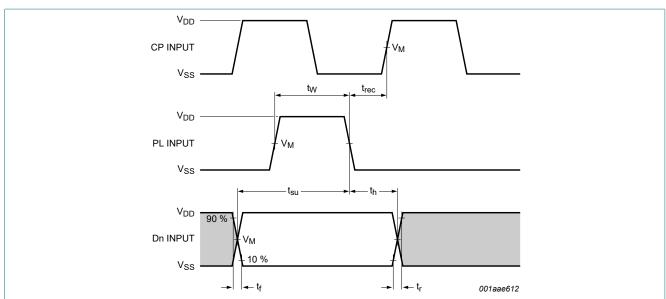
 $P_D$  can be calculated from the formulas shown.  $V_{SS} = 0$  V;  $t_r = t_f \le 20$  ns;  $T_{amb} = 25$  °C.

Symbol	Parameter	V <sub>DD</sub>	Typical formula for $P_D$ ( $\mu$ W)	where:
PD	dynamic power	5 V	$P_{D} = 900 \times f_{i} + \Sigma (f_{o} \times C_{L}) \times V_{DD}^{2}$	$f_i$ = input frequency in MHz
	dissipation	10 V	$P_{D} = 4300 \times f_{i} + \Sigma (f_{o} \times C_{L}) \times V_{DD}^{2}$	$f_o =$ output frequency in MHz C <sub>1</sub> = output load capacitance in pF
		15 V	$P_{D} = 12000 \times f_{i} + \Sigma (f_{o} \times C_{L}) \times V_{DD}^{2}$	$V_{DD}$ = supply voltage in V $\Sigma(f_o \times C_L)$ = sum of the outputs





#### 8-bit static shift register

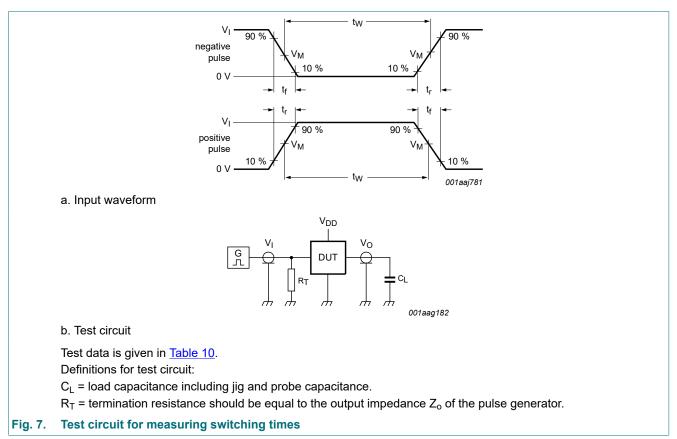


Set-up times and hold times are shown as positive values but may be specified as negative values. Measurement points are given in <u>Table 9</u>.

#### Fig. 6. Waveforms showing minimum pulse width and recovery time for PL; set-up and hold times for Dn to PL

#### **Table 9. Measurement points**

Supply voltage	Input	Output				
V <sub>DD</sub>	V <sub>M</sub>	V <sub>M</sub>	V <sub>X</sub>	V <sub>Y</sub>		
5 V to 15 V	0.5V <sub>DD</sub>	0.5V <sub>DD</sub>	0.1V <sub>DD</sub>	0.9V <sub>DD</sub>		



### 8-bit static shift register

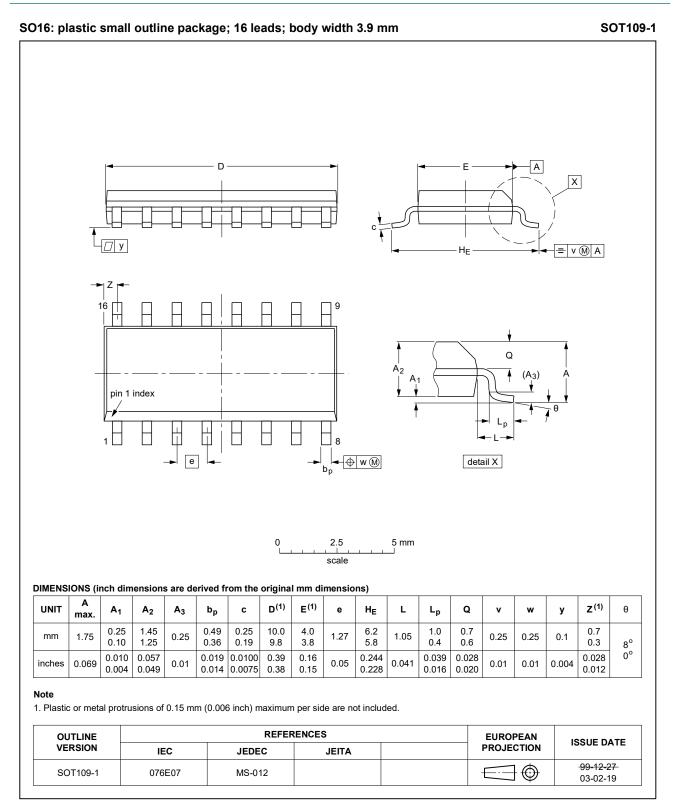
Table 10. Test data

Supply voltage	Input	Load	
V <sub>DD</sub>	VI	CL	
5 V to 15 V	$V_{SS}$ or $V_{DD}$	≤ 20 ns	50 pF

HEF4021B

#### 8-bit static shift register

### **11. Package outline**



#### Fig. 8. Package outline SOT109-1 (SO16)

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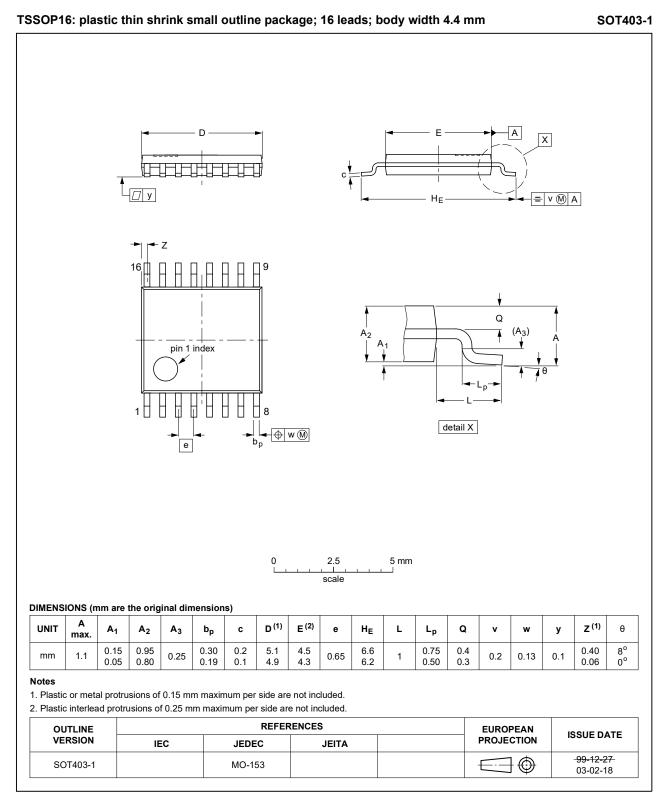


Fig. 9. Package outline SOT403-1 (TSSOP16)

HEF4021B

# 12. Abbreviations

Table 11. Abbreviations				
Acronym	Description			
CMOS	Complementary Metal-Oxide Semiconductor			
DUT	Device Under Test			
ESD	ElectroStatic Discharge			
НВМ	Human Body Model			
MM	Machine Model			

# 13. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes	
HEF4021B v.11	20211201	Product data sheet	-	HEF4021B v.10	
Modifications:	<ul> <li>The format of this data sheet has been redesigned to comply with the identity guidelines of Nexperia.</li> <li>Legal texts have been adapted to the new company name where appropriate.</li> <li><u>Section 2</u> updated.</li> <li><u>Table 4</u>: Derating values for P<sub>tot</sub> total power dissipation updated.</li> </ul>				
		-			
HEF4021B v.10	20160321	Product data sheet	-	HEF4021B v.9	
Modifications:	Type number HEF4021BP (SOT38-4) removed.				
HEF4021B v.9	20130830	Product data sheet	-	HEF4021B v.8	
Modifications:	Added type number HEF4021BTT.				
HEF4021B v.8	20111118	Product data sheet	-	HEF4021B v.7	
Modifications:	<ul> <li>Legal pages updated.</li> <li>Changes in <u>Section 1</u> and <u>Section 2</u>.</li> <li>Section "Applications" removed.</li> </ul>				
HEF4021B v.7	20111010	Product data sheet	-	HEF4021B v.6	
HEF4021B v.6	20091127	Product data sheet	-	HEF4021B v.5	
HEF4021B v.5	20090707	Product data sheet	-	HEF4021B v.4	
HEF4021B v.4	20081110	Product data sheet	-	HEF4021B_CNV v.3	
HEF4021B_CNV v.3	19950101	Product specification	-	HEF4021B_CNV v.2	
HEF4021B_CNV v.2	19950101	Product specification	-	-	

#### 8-bit static shift register

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#### Data sheet status

Document status [1][2]	Product status [3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
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